

Convergence and Stability of Graph Convolutional Networks on Large Random Graphs

Nicolas Keriven¹, Alberto Bietti², Samuel Vaiter³

¹CNRS, GIPSA-lab

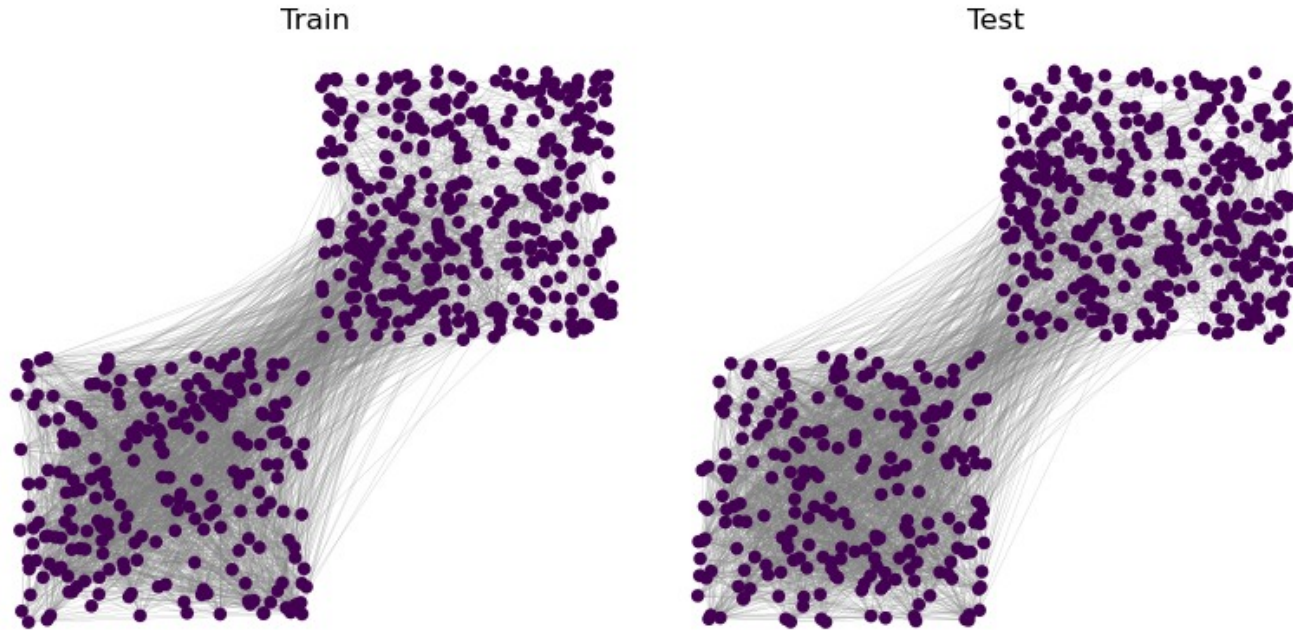
²NYU Center for Data Science

³CNRS, IMB

`nicolas.keriven@gipsa-lab.grenoble-inp.fr`

Training GNNs

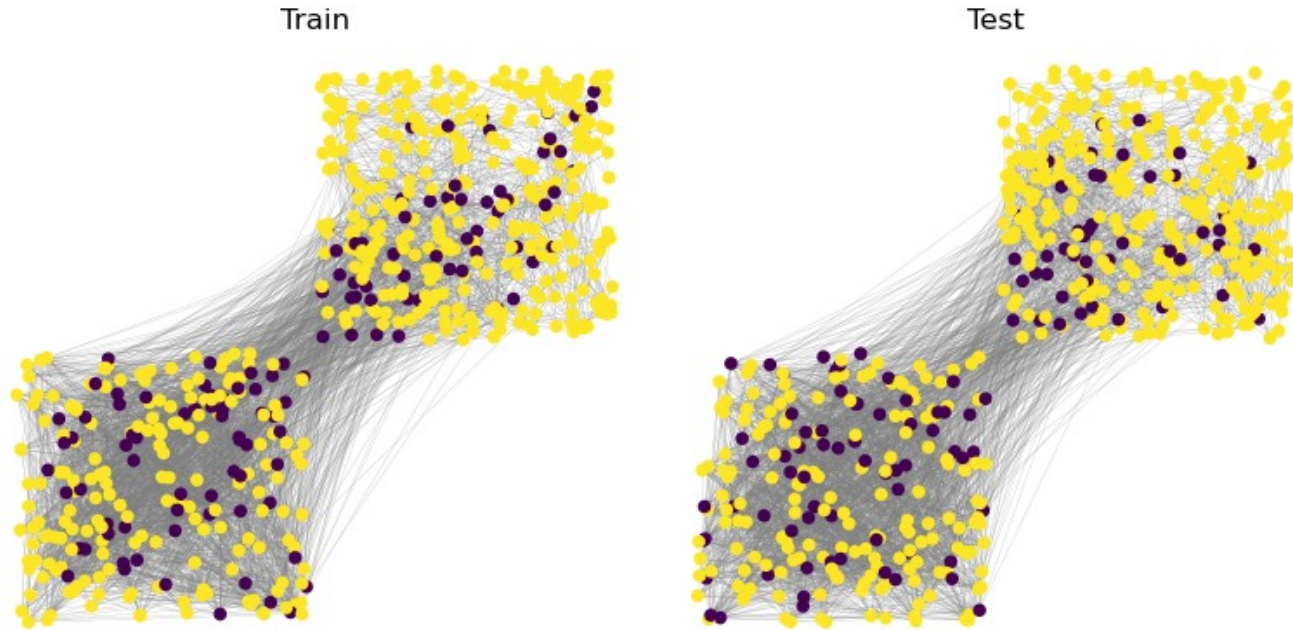
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*Output of a GNN with only graph structure as input,
on two **different** graphs that “look the same”*

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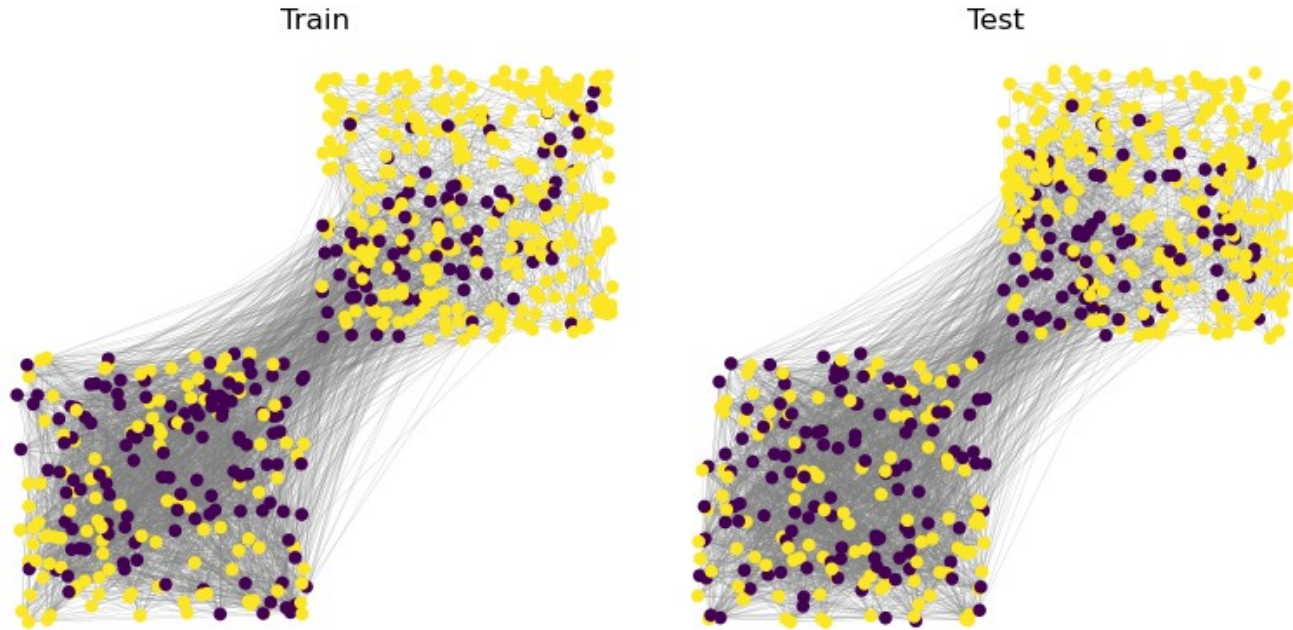
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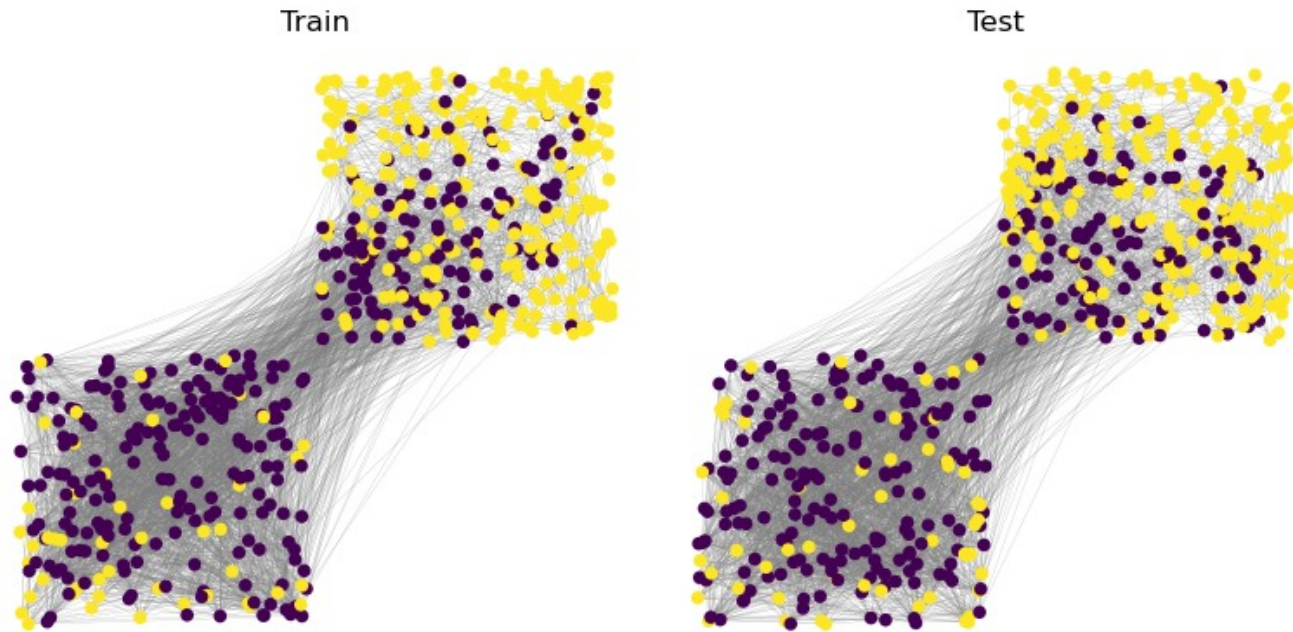
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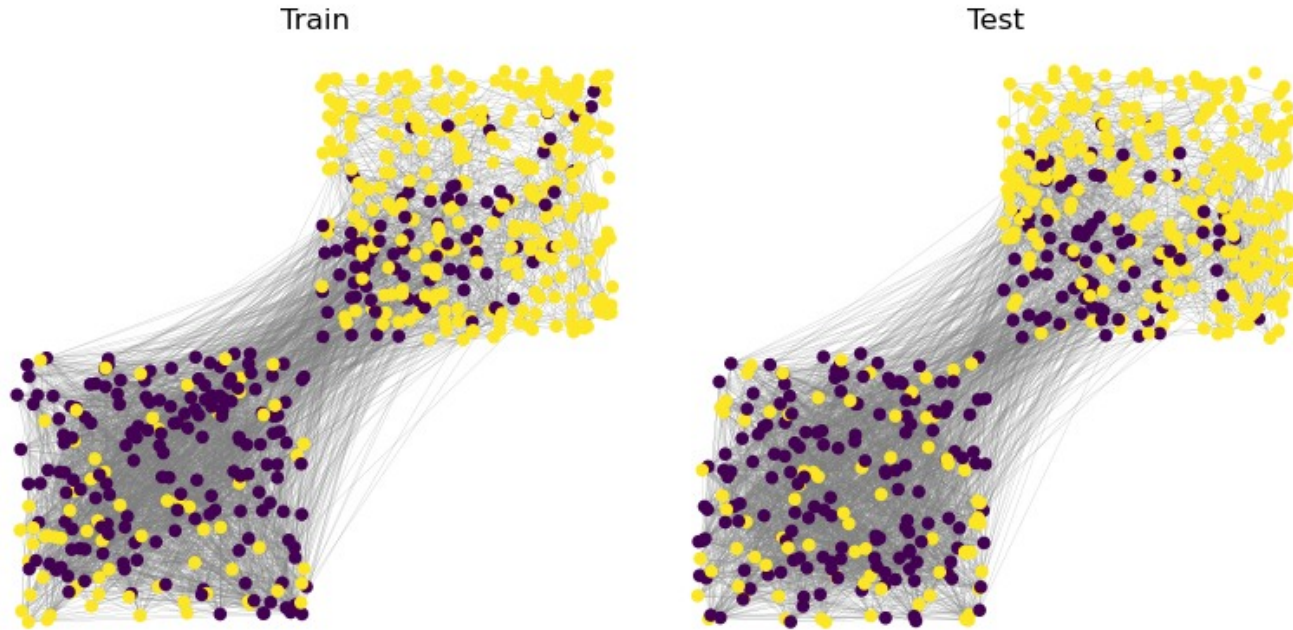
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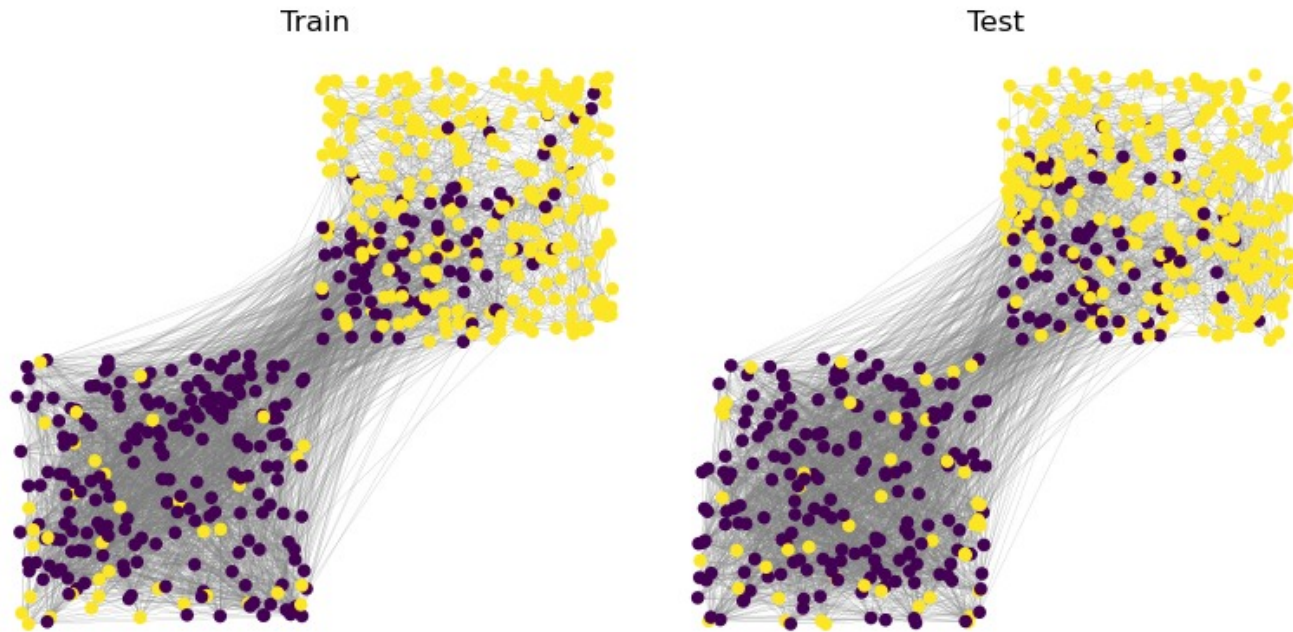
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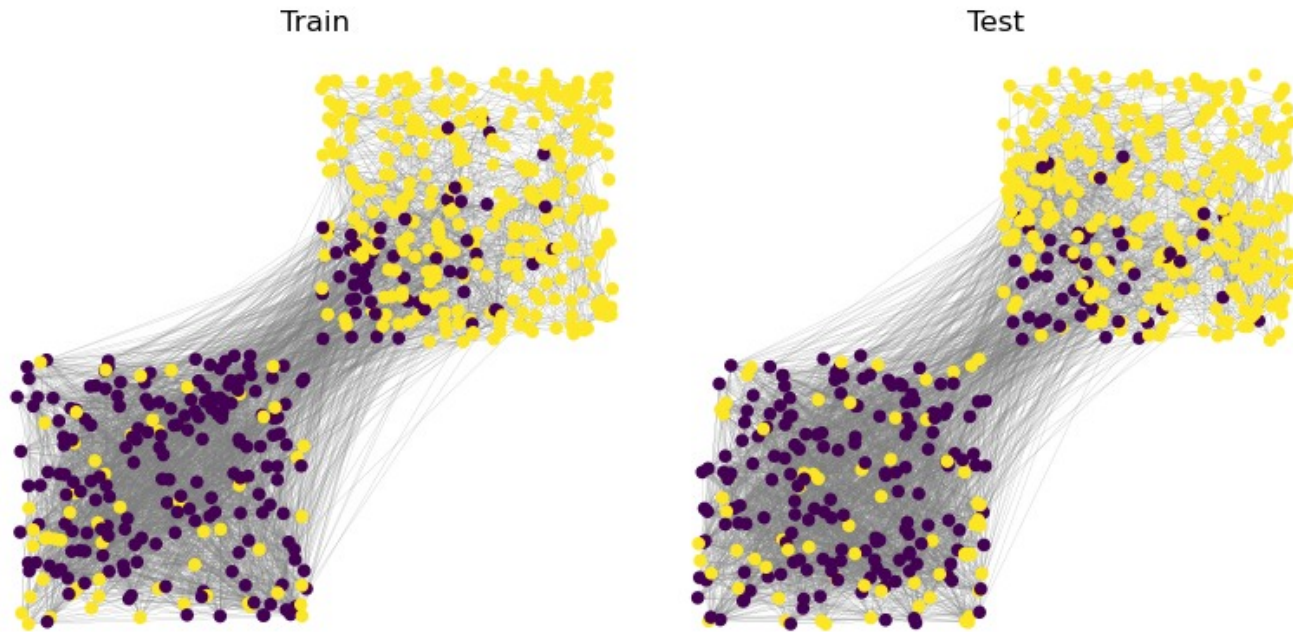
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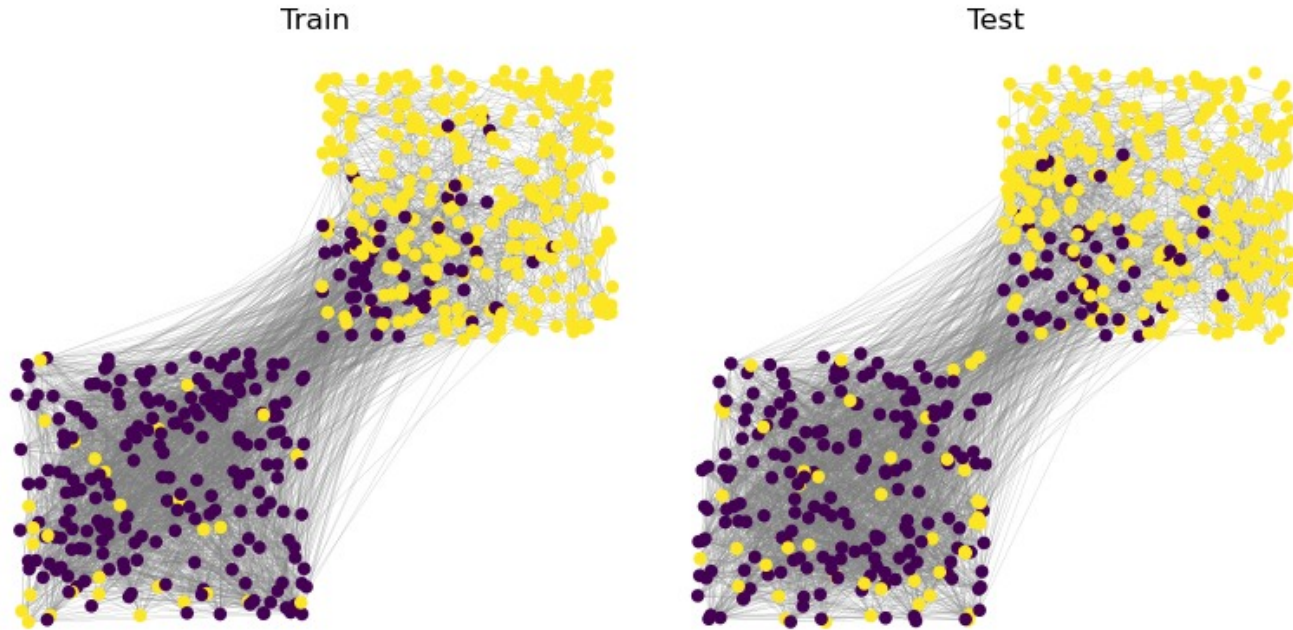
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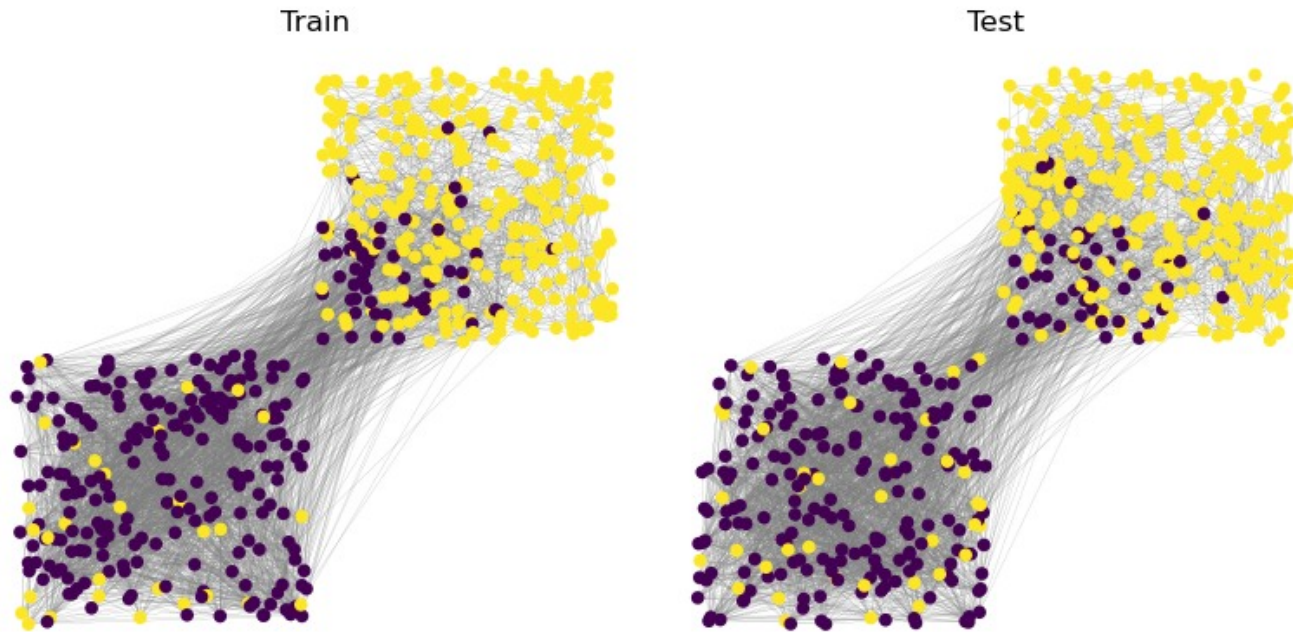
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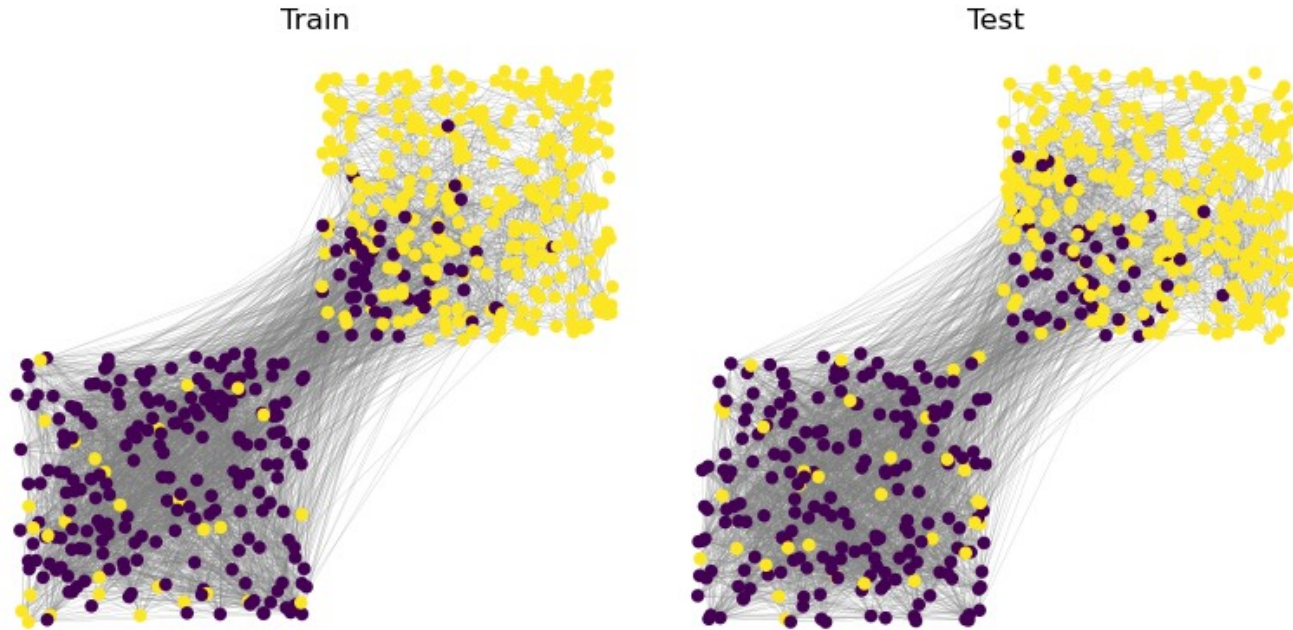
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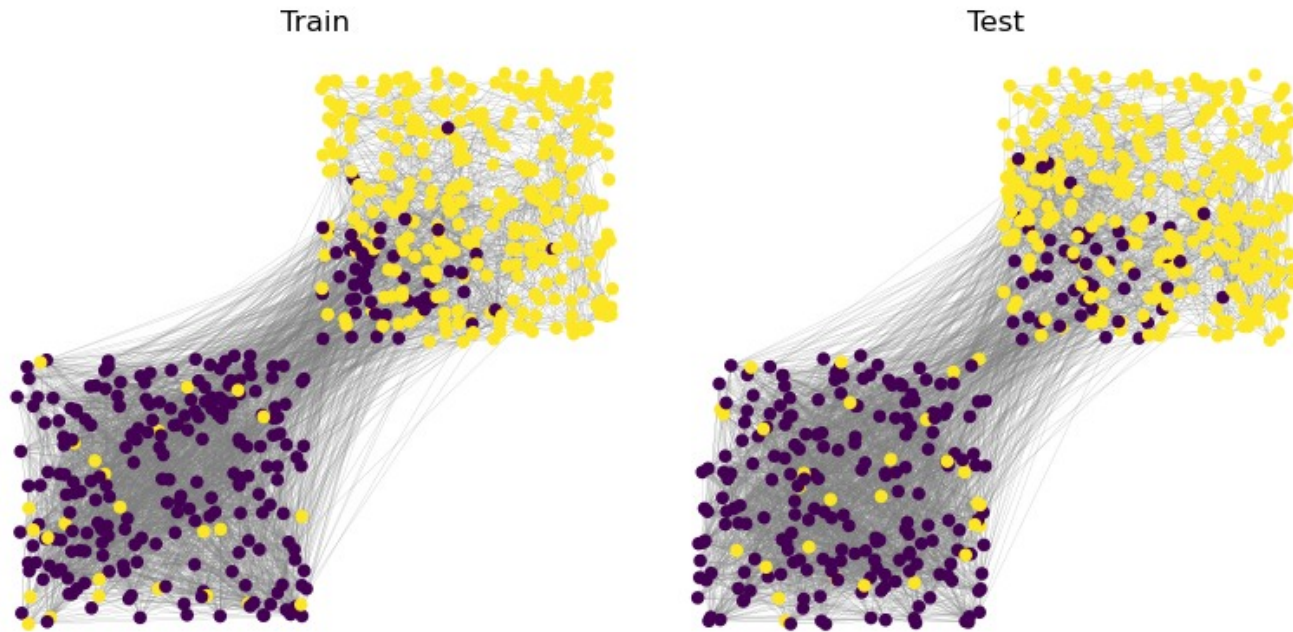
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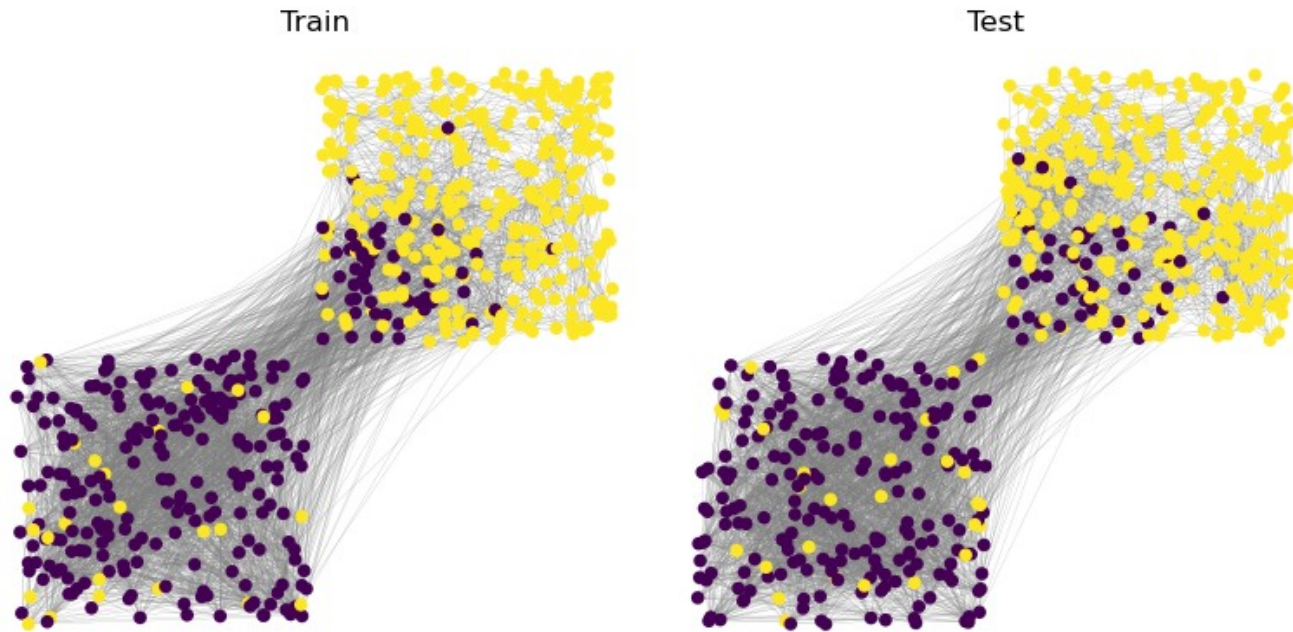
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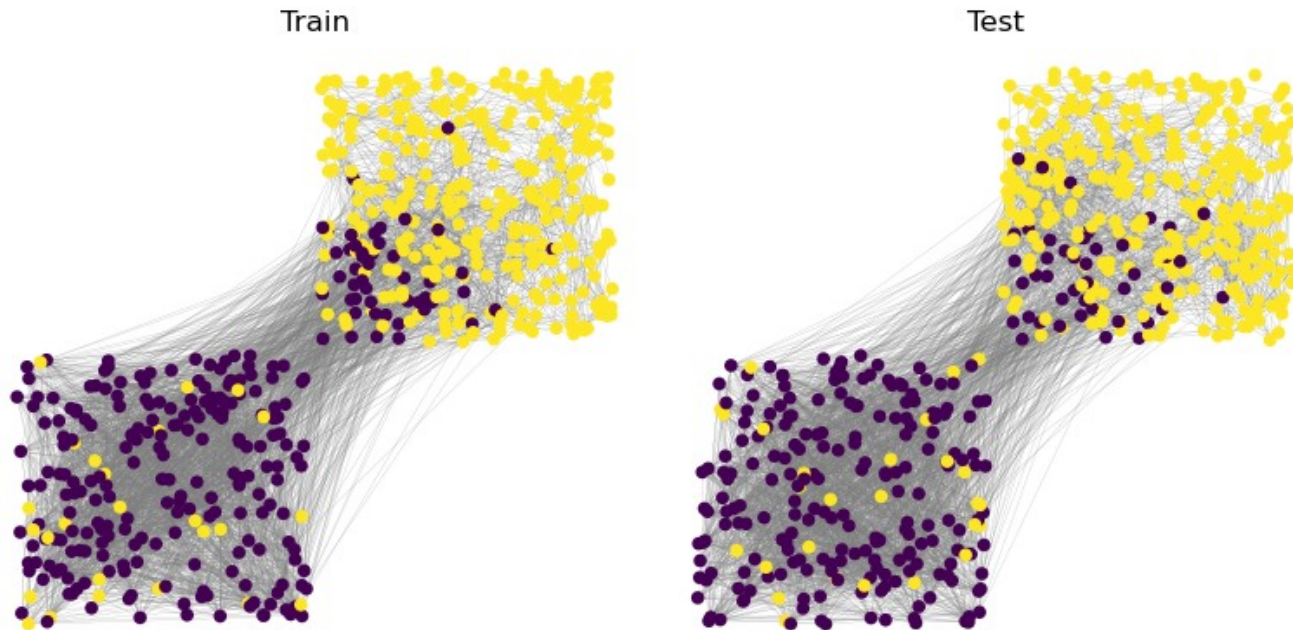
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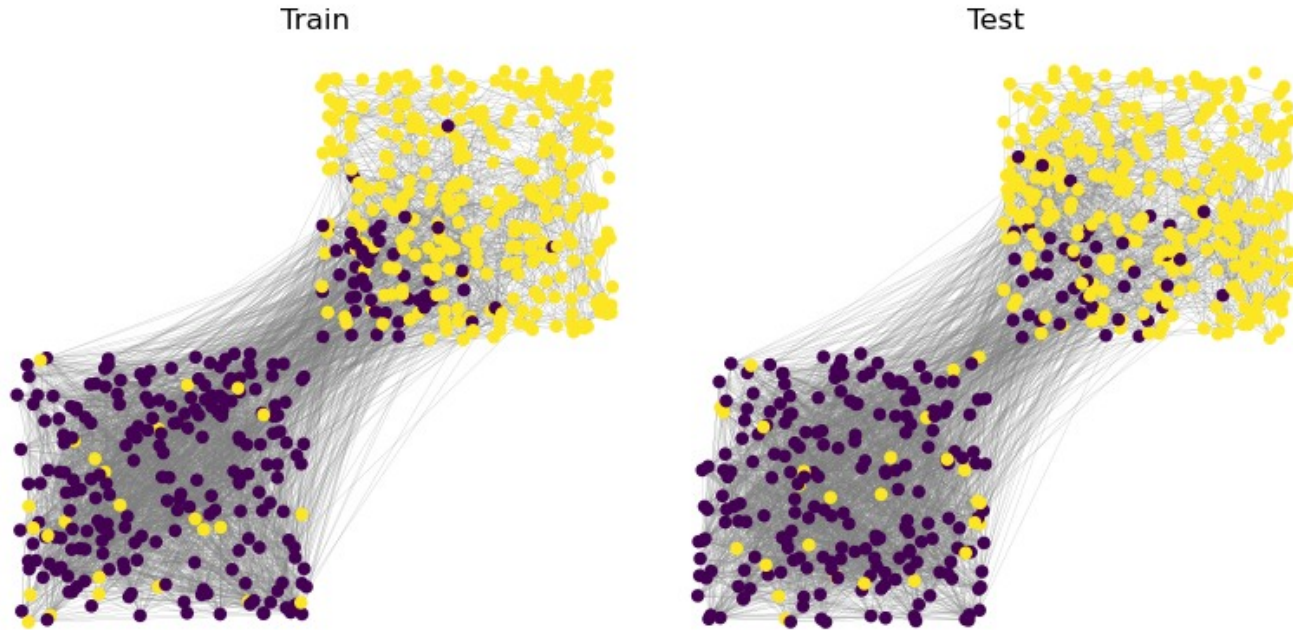
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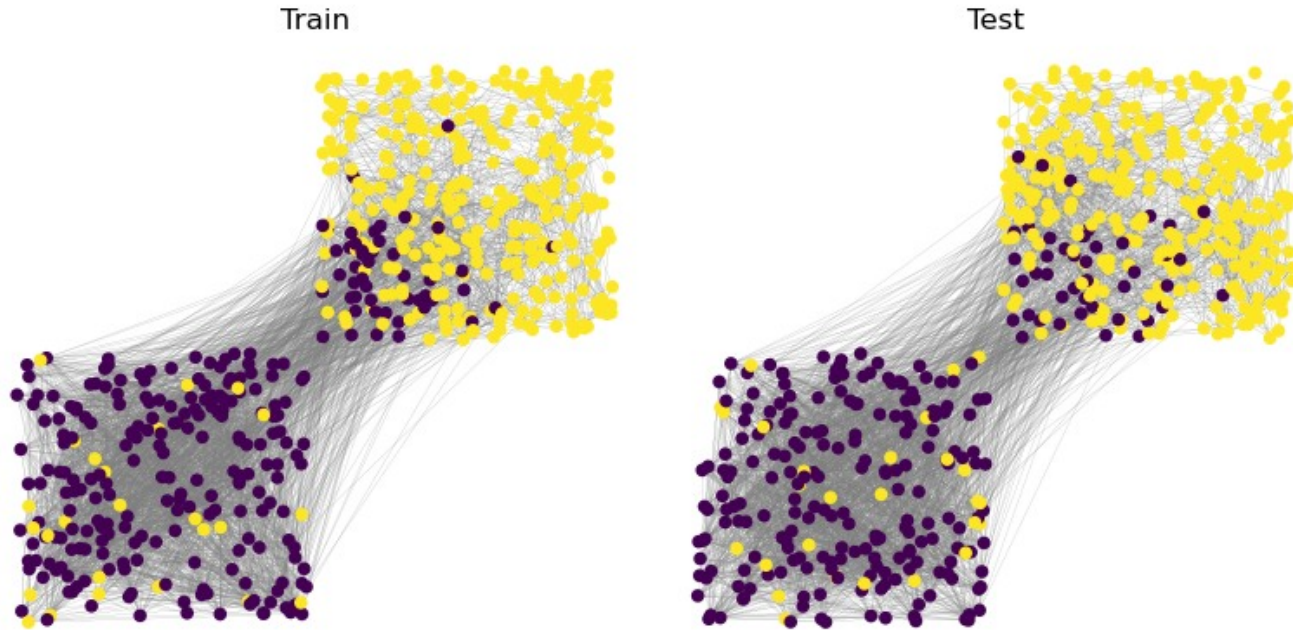


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- When are two large graphs “similar” ? Does a GNN give “similar” outputs ?

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- In this talk: (some) properties of GNNs on large **random latent-position models** of graphs

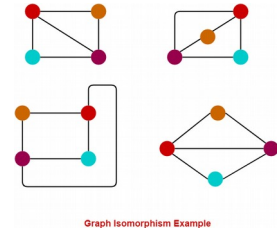
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(Some) background in GNN theoretical analysis...

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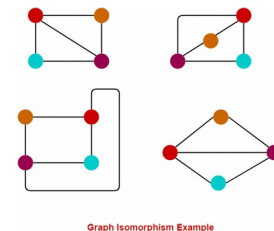
- As powerful as WL-test to distinguish **graph isomorphism** [Xu et al. 2018]
- Can be made as powerful as k-WL-test... [Maron et al. 2019]



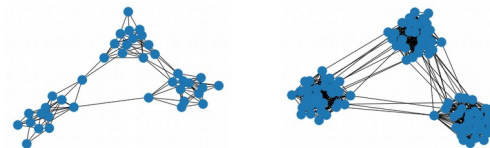
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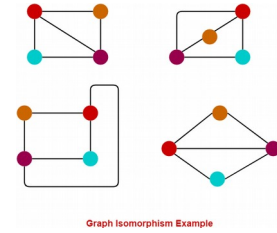
What about “large” graphs ?
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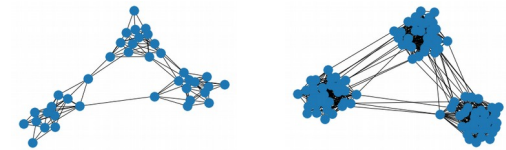
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- **Stability** to input change
- **CNN** (translation-invariant): robustness to deformation [Mallat, Bruna, Bietti, Mairal]

$$\|\Phi(f) - \Phi(f \circ (Id - \tau))\| \leq \|\nabla \tau\|_{\infty}$$

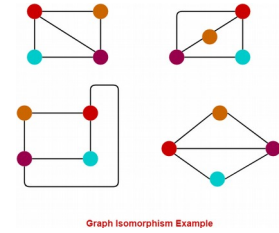
- **GNN**: stability to **discrete graph metrics** [Gama et al. 2019]

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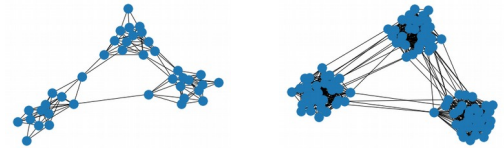
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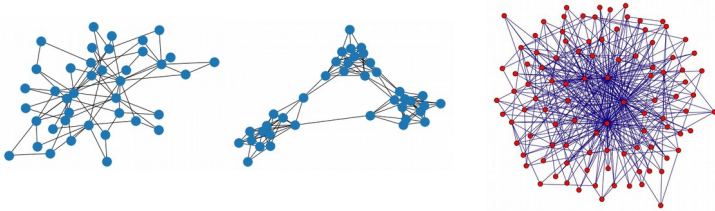
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What is a meaningful
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Random Graphs

Long history of modeling large graphs with **random generative models**



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Chung and Lu. *Complex Graphs and Networks* (2004)

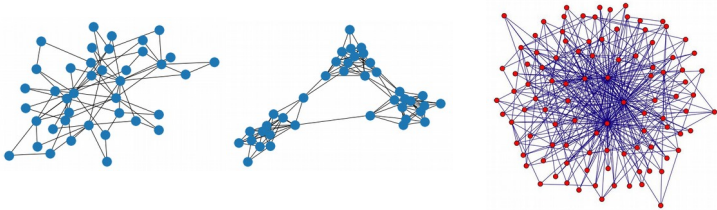
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Latent position model

(W -random graphs, kernel random graphs...)

$$x_i \sim P \in \mathbb{R}^d$$

Latent variables

$$z_i = f_0(x_i)$$

Node features

$$a_{ij} \sim \text{Ber}(\alpha_n W(x_i, x_j))$$

Connectivity kernel

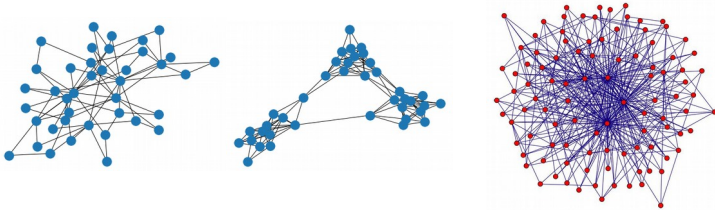
Sparsity level:

$$\text{Dense } \alpha_n \sim 1 \quad \text{Sparse } \alpha_n \sim 1/n$$

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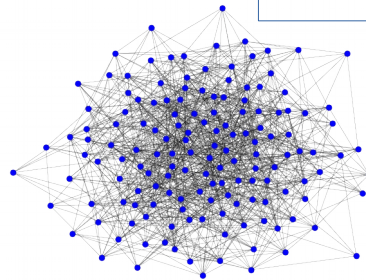
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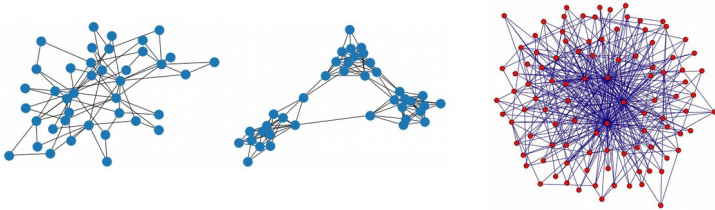
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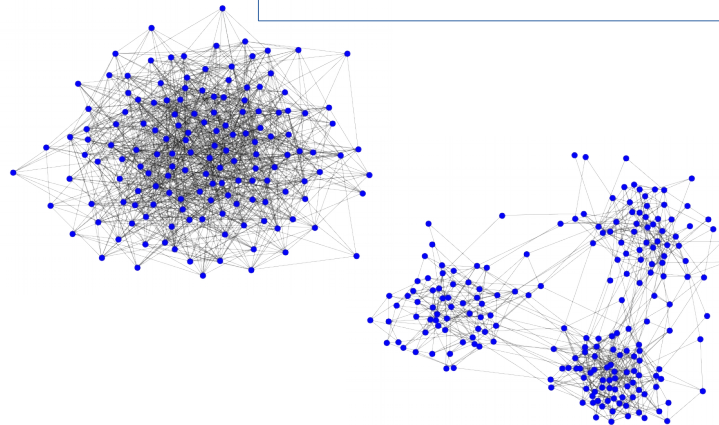
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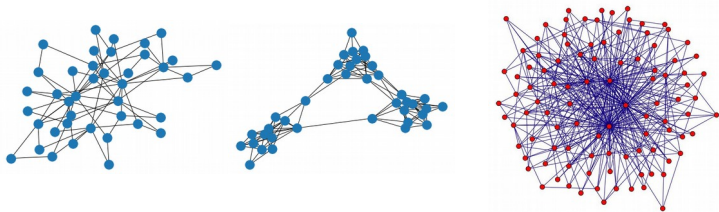
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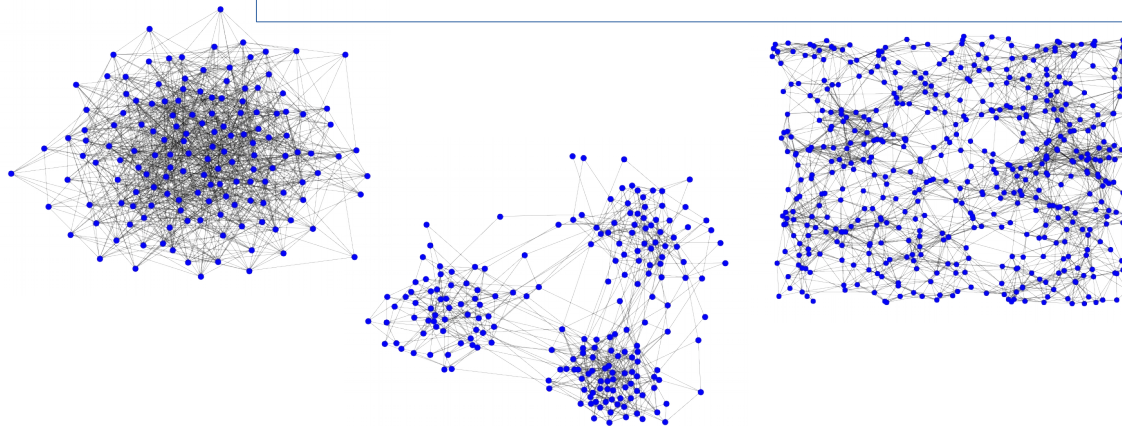
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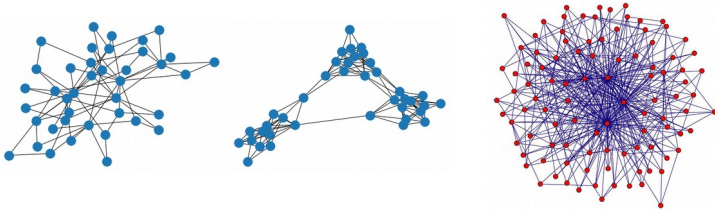
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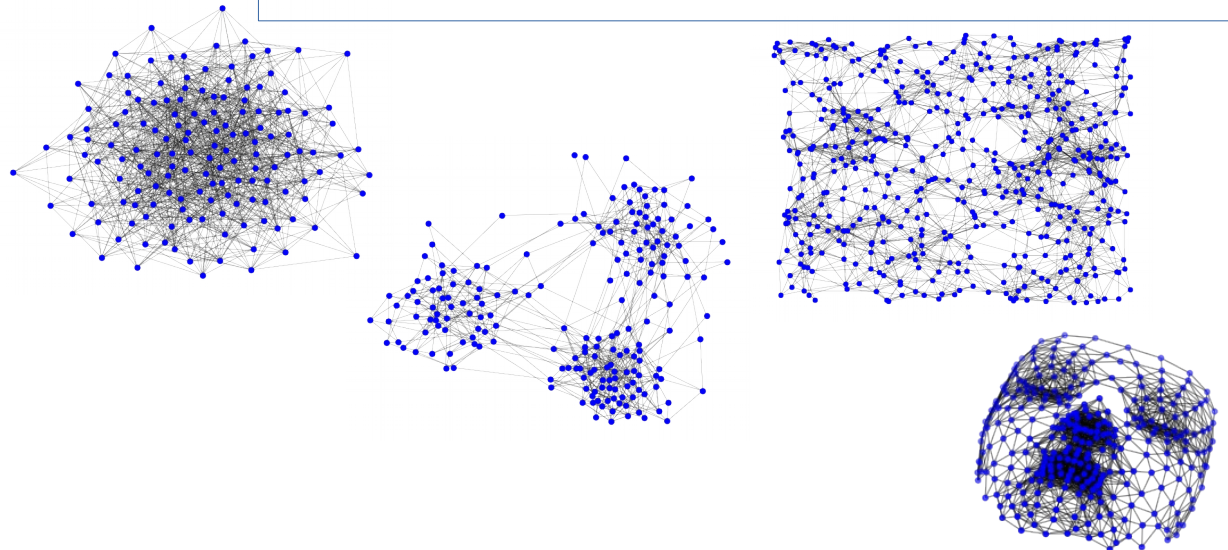
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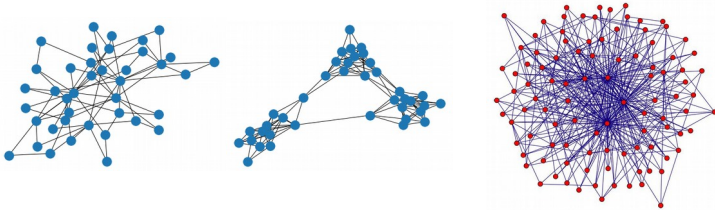
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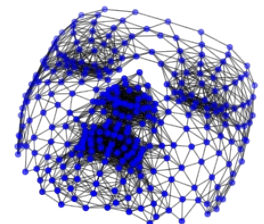
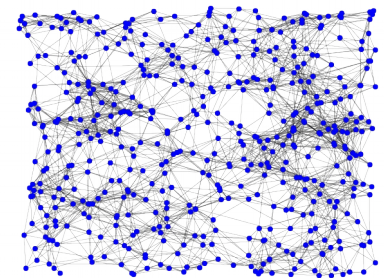
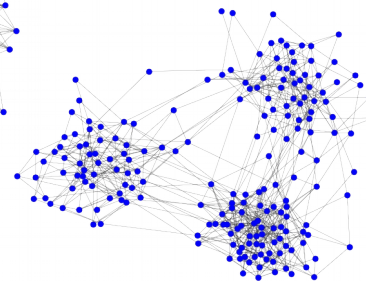
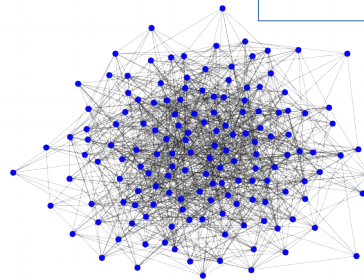
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NB: all the above can be formulated with **translation-invariant kernels**

GNN convergence

(Spectral) Graph Neural Networks

- Propagate **signal over nodes**

$$z_j^{(\ell+1)} = \rho \left(\sum_i h_{ij}^{(\ell)} (L) z_i^{(\ell)} + b_j^{(\ell)} 1_n \right)$$

Polynomial graph filters
with normalized Laplacian $L = D^{-\frac{1}{2}} A D^{-\frac{1}{2}}$

By default **equivariant**, final pooling for **invariant**

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If $\alpha_n \gtrsim (\log n)/n$, with probability $1 - n^{-r}$, the deviation between discrete and continuous GNN is at most $O(dn^{-1/2} + (\alpha_n n)^{-1/2})$

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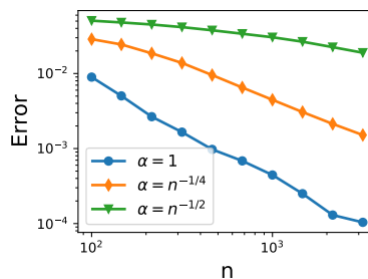
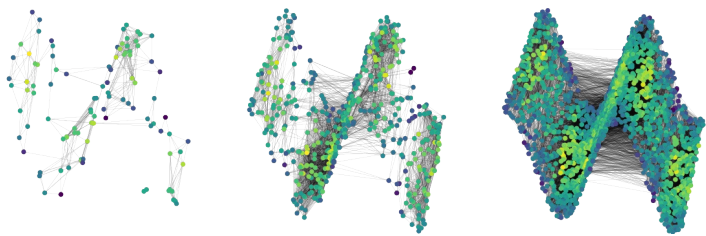
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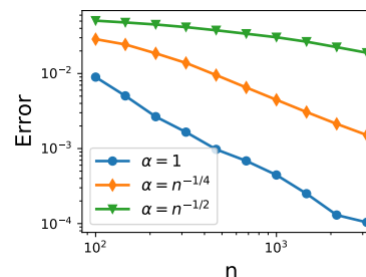
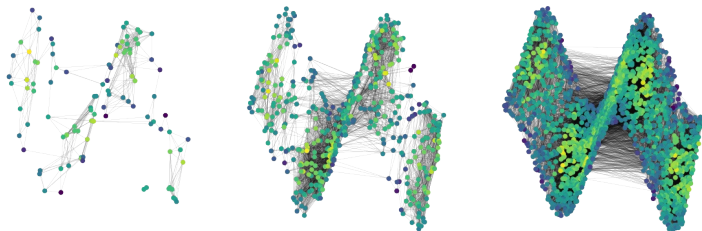
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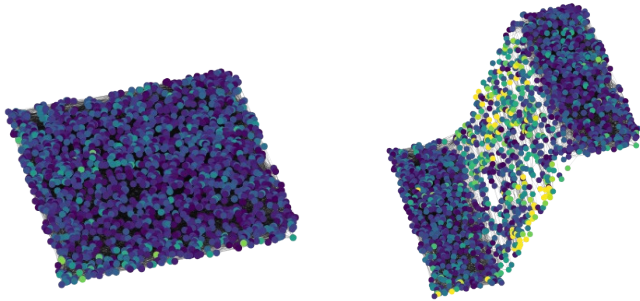
continuous GNN is at most $O(dn^{-1/2} + (\alpha_n n)^{-1/2})$



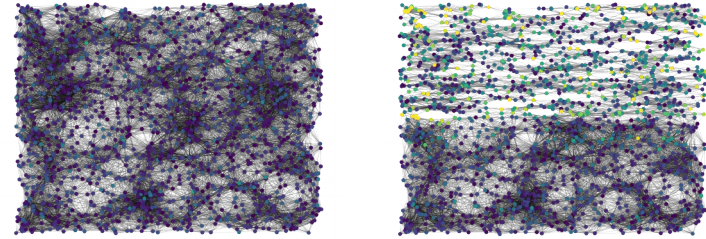
NB: Thanks to normalized Laplacian, the limit does **not** depend on α_n but the rate of convergence does...

Random Graphs: stability

Latent position models allow to define **intuitive geometric deformations**



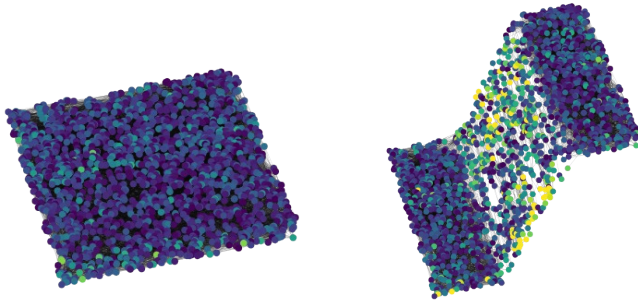
Deformation of distribution



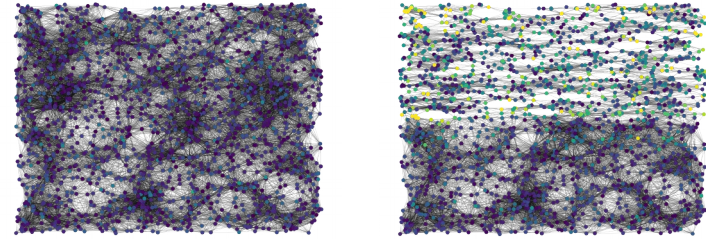
Deformation of kernel

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Deformation of distribution



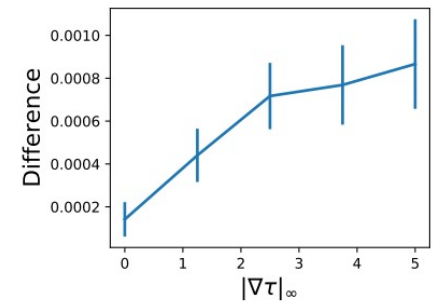
Deformation of kernel

Thm (Stability, simplified)

For **translation-invariant** kernels, if:

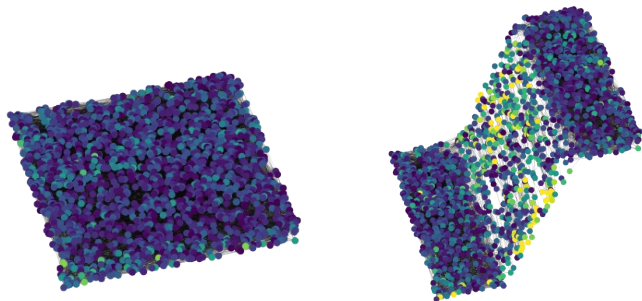
- W is replaced by $W(x - \tau(x), x' - \tau(x'))$, or
- P is replaced by $(Id - \tau)\#P$ (and f_0 is translated), or
- f_0 is replaced by $f_0 \circ (Id - \tau)$

Then, the deviation of c-GNN is bounded by $\|\nabla\tau\|_\infty$

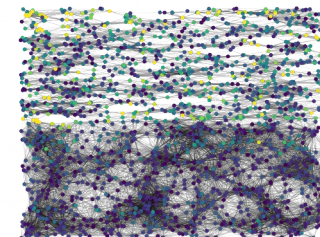
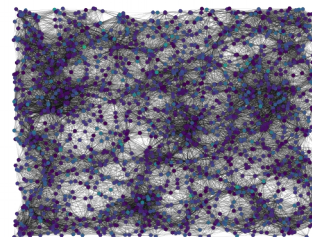


Random Graphs: stability

Latent position models allow to define **intuitive geometric deformations**



Deformation of distribution



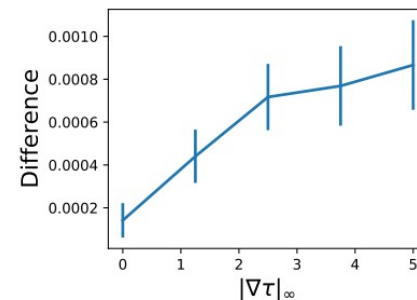
Deformation of kernel

Thm (Stability, simplified)

For **translation-invariant** kernels, if:

- W is replaced by $W(x - \tau(x), x' - \tau(x'))$, or
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Then, the deviation of c-GNN is bounded by $\|\nabla\tau\|_\infty$



Outlooks: approximation power, generalization, optimization, other RG models...