

Seeking universal approximation for continuous limits of GNNs on large random graphs

Matthieu Cordonnier¹, **Nicolas Keriven**², Nicolas Tremblay¹, Samuel Vaiter³

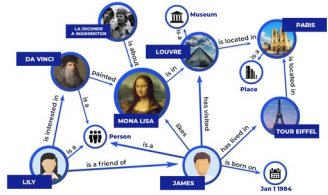
¹CNRS, Gipsa-lab, Univ. Grenoble-Alpes

²CNRS, IRISA

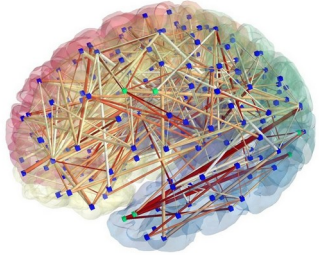
³CNRS, LJAD



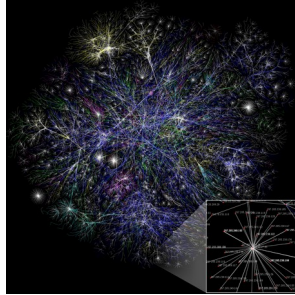
Graphs and large graphs



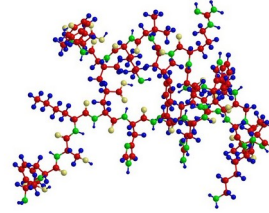
Database/Knowledge graph



Brain connectivity network



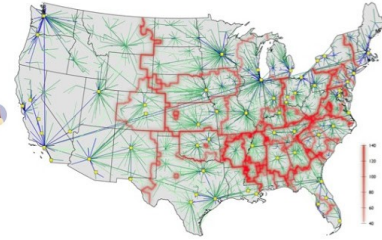
Internet



Molecule



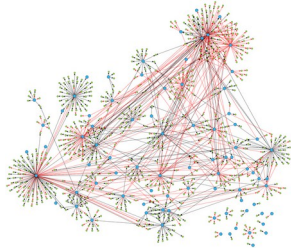
Social network



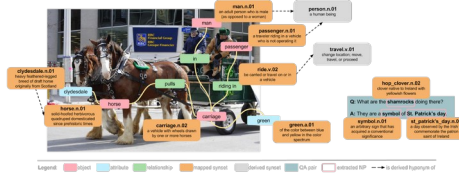
Transportation network



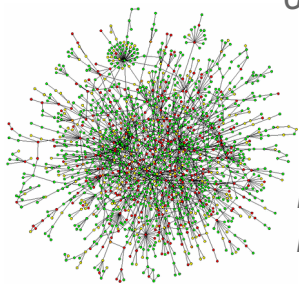
Computer network



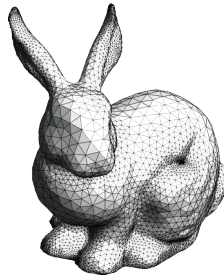
Gene regulatory network



Scene understanding network



Protein interaction network

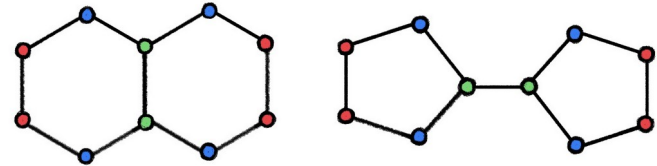


3D mesh

- **Many types of data** can be represented as graphs
"if all you have is a hammer, everything looks like a nail"
- Many of these graphs are **large**, with **macroscopic properties**
- **GNNs** have become the *de-facto* state-of-the-art models

GNNs and large graphs?

- (Even) compared to regular NNs, many properties of GNNs are **still quite mysterious**.
 - Eg: **universality** of NNs is known since the 90s, for GNNs it is still a very active field.
- Most analyses of GNNs are **discrete/combinatorial** in nature.
 - **WL-test**: Can a GNN distinguish two **non-isomorphic** graphs?
 - Can a GNN count triangles? compute the diameter of a graph? etc.

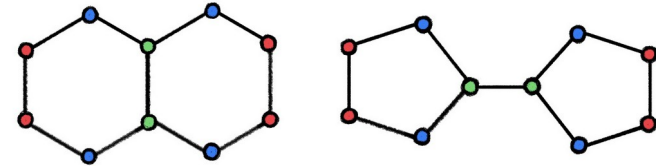


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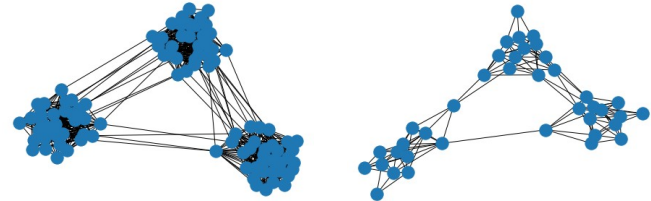
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- **Large graphs** may “**look the same**”, but are never isomorphic, of different size, etc.

- A recent trend is to use **statistical graph models** to understand GNNs’ macroscopic behaviors
[see works by Ruiz et al., Levie et al., Keriven et al...]

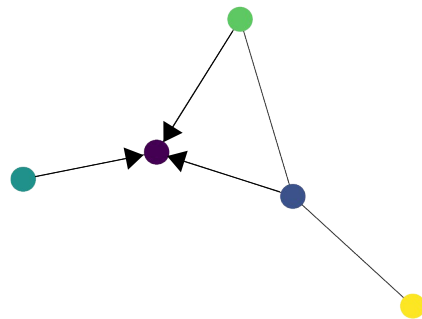


“From discrete to continuous”

GNNs

Most GNNs are based on **message-passing**

$$z_i^{(\ell+1)} = \text{AGG}(z_i^{(\ell)}, \{z_j^{(\ell)}\}_{j \in \mathcal{N}(i)})$$

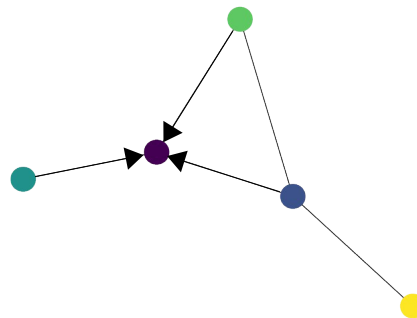


At each layer, each node receives "messages" from its neighbors.

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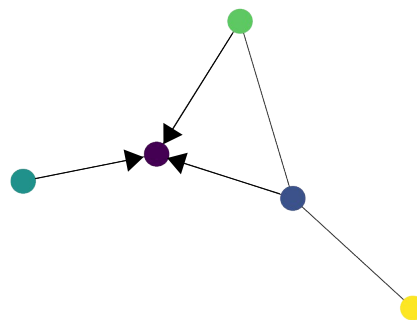
Classical: use of a **graph matrix** S (normalized adjacency, normalized Laplacian...)

$$Z^{(\ell+1)} = \rho \left(Z^{(\ell)} \theta_0^{(\ell)} + \mathbf{S} Z^{(\ell)} \theta_1^{(\ell)} + \mathbf{1}_n (b^{(\ell)})^\top \right) \in \mathbb{R}^{n \times d_\ell}$$

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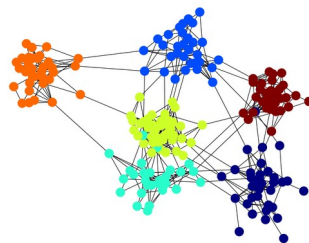
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Output **node labels**:

$$\Phi_\theta(S, Z^{(0)}) = Z^{(L)} \theta^{(L)} + \mathbf{1}_n (b^{(L)})^\top$$



Can also perform “global pooling” to compute whole graph quantity

$$\frac{1}{n} \sum_i z_i^{(\ell)}$$

(Example of most) random graphs

Long history of modelling large graphs with
random generative models

Chung and Lu. *Complex Graphs and Networks* (2004)

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Latent position models (*W-random graphs, kernel random graphs, graphon...*)

$$x_1, \dots, x_n \stackrel{iid}{\sim} P_x$$

Unknown latent variables in
a **latent space** \mathcal{X}

$$a_{ij} \sim P_e(\cdot \mid x_i, x_j)$$

(most often) **independent Edges**

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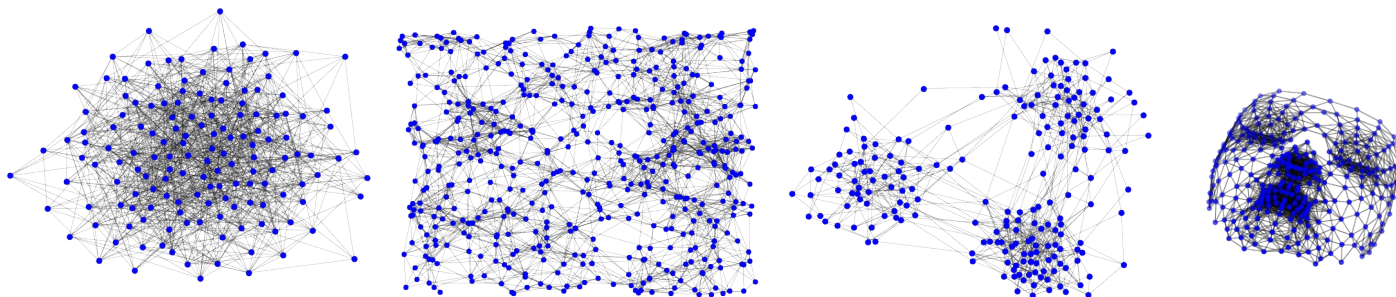
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(most often) **independent Edges**

Ex:

$$a_{ij} \sim \text{Ber}(W_n(x_i, x_j))$$

W_n may vary with n to
model **graph sparsity**



*Includes Erdős-Rényi,
Stochastic Block Models,
Gaussian kernel, epsilon-
graphs...*

Continuous GNNs

In many cases, S will “converge” to an **operator** \mathbf{S} (ex: adjacency to kernel integral operator T_W)

One can then define a **continuous GNN** that propagates **functions over the latent space**:

$$f^{(\ell+1)} = \rho \left((\theta_0^{(\ell)})^\top f^{(\ell)} + (\theta_1^{(\ell)})^\top \mathbf{S} f^{(\ell)} + b^{(\ell)} \right) \in L^2(\mathbb{R}^{d_\ell}, P)$$

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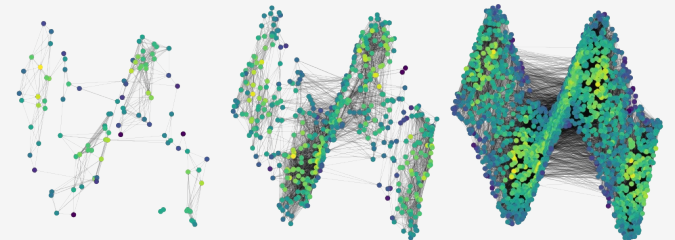
Example of convergence result:

$$\|\cdot\|_{\text{MSE}}^2 = \frac{1}{n} \|\cdot\|_F^2, \quad \iota_X f = [f(x_i)]_{i=1}^n$$

If, for all f : $\|S \iota_X f - \iota_X \mathbf{S} f\|_{\text{MSE}} \xrightarrow[n \rightarrow \infty]{\mathcal{P}} 0$

Then: $\|\Phi_\theta(S, \iota_X f^{(0)}) - \iota_X \Phi_\theta(\mathbf{S}, f^{(0)})\|_{\text{MSE}} \xrightarrow[n \rightarrow \infty]{\mathcal{P}} 0$

GNN applied to a sampled function converge to the sampled output of the cGNN



Valid for adjacency, Laplacian, degree-normalized versions...

Expressivity of cGNNs

$$\Phi_{\theta}(\mathbf{S}, \cdot) : L^2(\mathcal{X}, P) \rightarrow L^2(\mathcal{X}, P)$$

Expressivity of cGNNs have been examined a few times:

- [Keriven, Vaiter. *NeurIPS 2023*]: for a fixed input signal, **range of output functions**
- [Boker et al. *NeurIPS 2023*]: extension of **WL-test to graphons** (ie for graph-tasks)

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Def: Universality For all: $\mathcal{K} \subset L^2$ compact, \mathcal{T} operator, $\epsilon > 0$

There exists θ such that

$$\sup_{f \in \mathcal{K}} \|\Phi_{\theta}(f) - \mathcal{T}(f)\|_{L^2} \leq \epsilon$$

Neural Operators

This is reminiscent of **Neural Operators** [Tianping & Hong 1995, Lu et al. 2021]

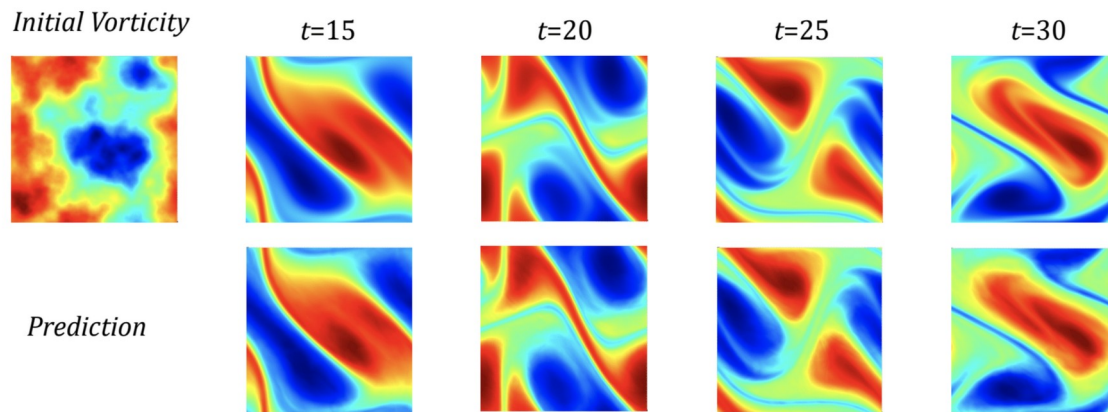
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$$\Phi_{\theta} \approx \mathcal{T} : \mathcal{A} \rightarrow \mathcal{B}$$

- Used a lot to solve PDEs



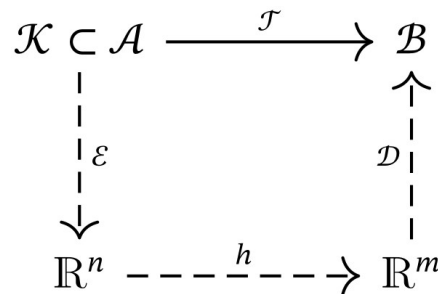
[Li et al. 2021]

- Universality known since the 90s! [Tianping & Hong 1995]

Universal Neural Operators? 1/2

How does one construct universal NOs?

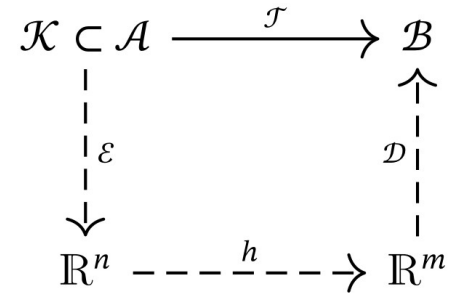
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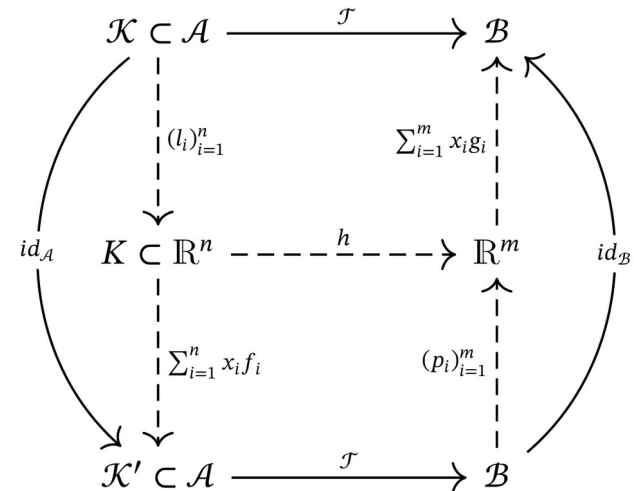
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When is this possible?

When one can construct **finite-rank operators** converging to **identity**

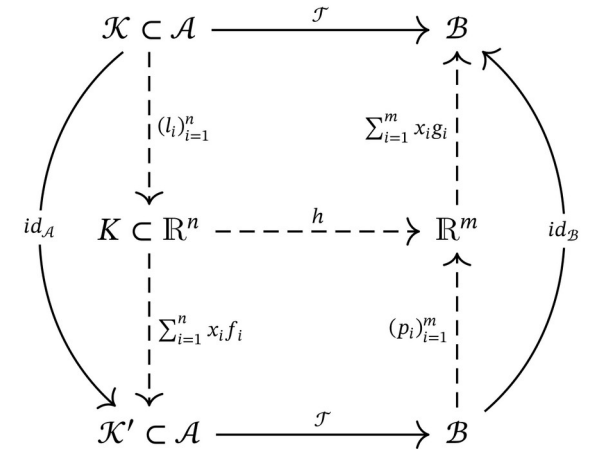
→ so-called *approximation property* of Banach spaces



Universal Neural Operators? 2/2

For instance, in Hilbert spaces \mathcal{A}, \mathcal{B} , with bases $\{\phi_i\}, \{\psi_j\}$

$$\sum_{j=1}^m \text{MLP}_{\theta_j}([\langle f, \phi_i \rangle]_{i=1}^m) \psi_j \quad \text{is universal}$$

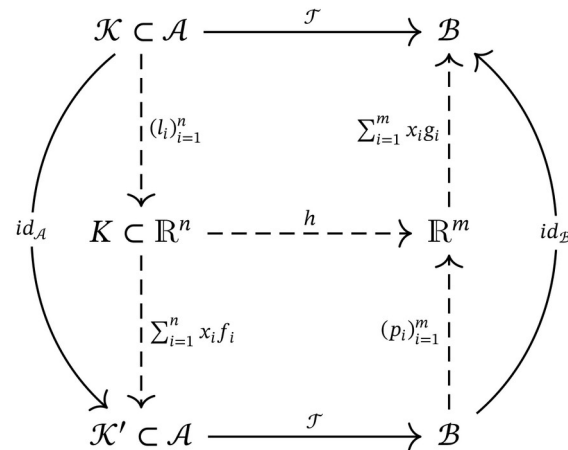


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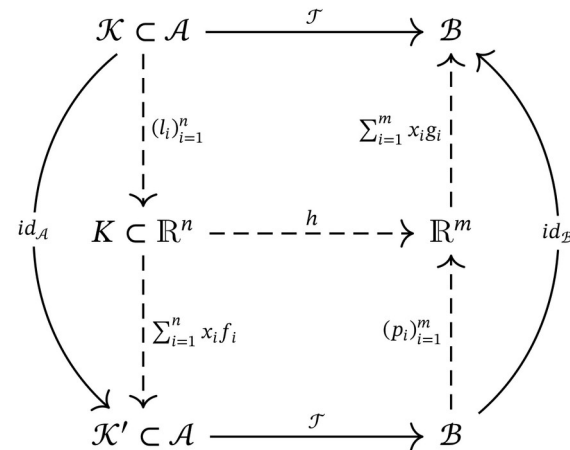


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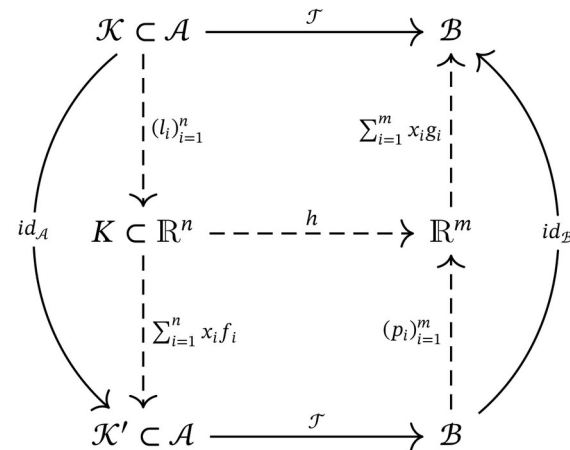
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How do we recover a basis of $L^2(\mathcal{X}, P)$ from \mathbf{S}, f ?

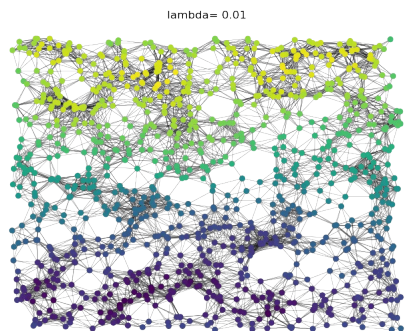
A spectral approach

Assume \mathbf{S} is full-rank \rightarrow the eigenfunctions $\{\phi_i\}$ are a basis of L^2

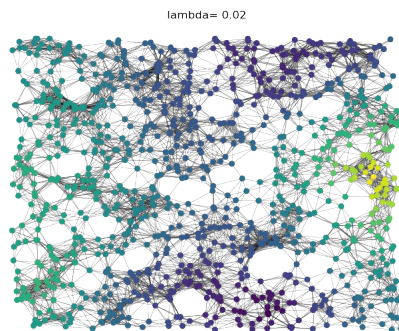
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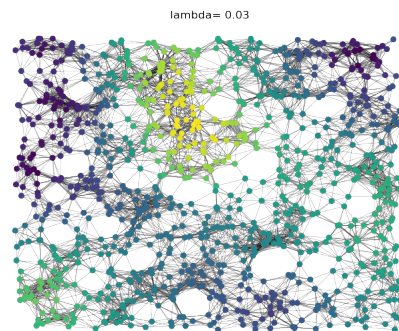
Can we just diagonalize $\mathcal{S} \approx \mathbf{S}$? \rightarrow we know $v_i \approx \iota_X \phi_i$



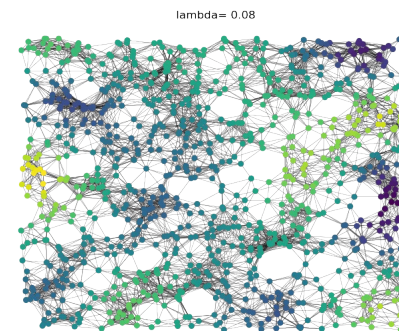
v_1



v_3



v_5



v_{10}

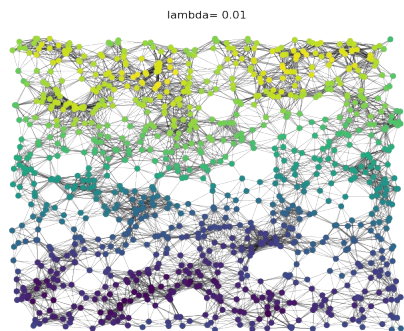
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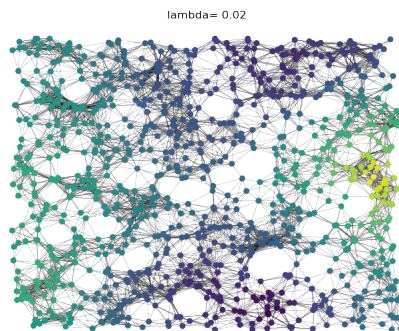
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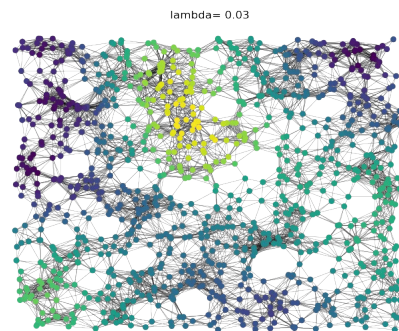
1) GNNs cannot directly diagonalize (... but not a real pbm: Positional Encoding, or clever filtering)



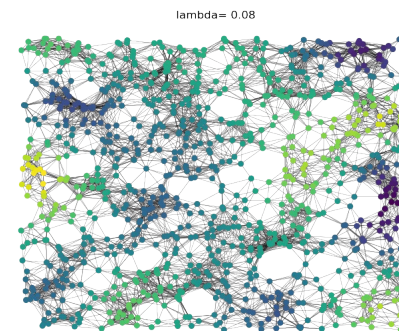
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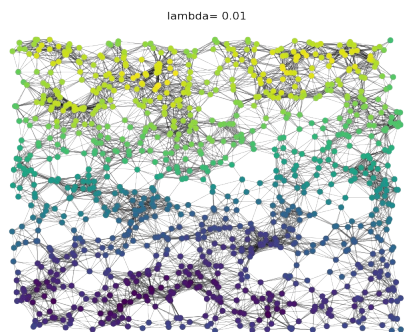
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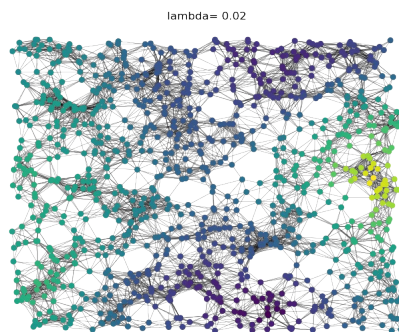
2) **Sign(/basis) indeterminacy**: cannot generalize!

output = $\{\text{random_sign}_i \phi_i\}$

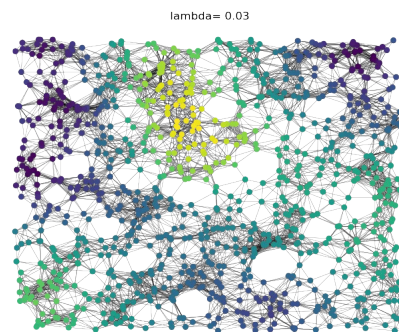
at each new graph/diagonalization algorithm



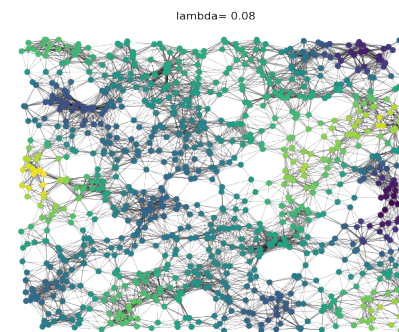
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Sign indeterminacy?

- Not a problem for **filtering**:

$$h(\mathbf{S})f = \sum_i h(\lambda_i) \underbrace{\langle f, \phi_i \rangle \phi_i}_{\text{Invariant to sign change!}}$$

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- Very much a problem for us!

$$\sum_{j=1}^m \text{MLP}_{\theta_j} \left([\langle f, \phi_i \rangle]_{i=1}^m \right) \phi_j$$

MLP : $\mathbb{R}^m \rightarrow \mathbb{R}$ \uparrow has no reason to be sign invariant for each coordinate!

Sign indeterminacy: quick fix

Assume \mathbf{S} is full-rank (with simple eigenvalues)

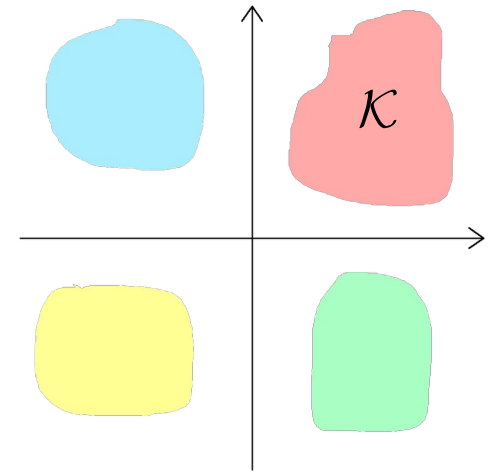
We are working **within a compact of functions** anyway, let's assume that it is in a **fixed orthant**

Assume: $\mathcal{K} \subset \mathcal{D}^+$

\mathcal{D}^+ s.t. there exists $\{\phi_i\}$ basis of eigenfunctions of \mathbf{S} s.t.

$$\forall f \in \mathcal{D}^+, i \geq 1 \quad \langle f, \phi_i \rangle_{L^2} > 0$$

w.l.o.g.



A spectral N0

A spectral approach:

$$\Phi_{\theta}(\mathbf{S}, f) =$$

1) Diagonalize $\mathbf{S} \rightarrow \phi_1, \dots, \phi_m$

2) Solve sign indeterminacy by $\phi_i \leftarrow \text{sign}(\langle f, \phi_i \rangle) \phi_i$

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Theorem:

Universal on domains $\mathcal{K} \subset \mathcal{D}^+$

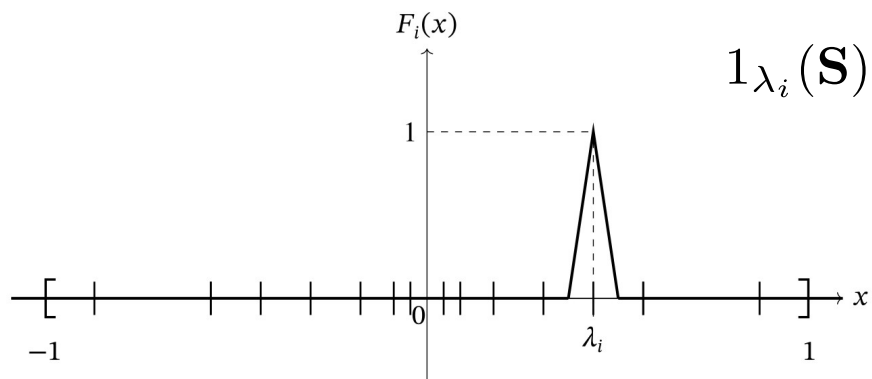
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Since eigenvalues are separated and $\mathcal{K} \subset \mathcal{D}^+$, ϕ_i can be recovered by filtering and normalization



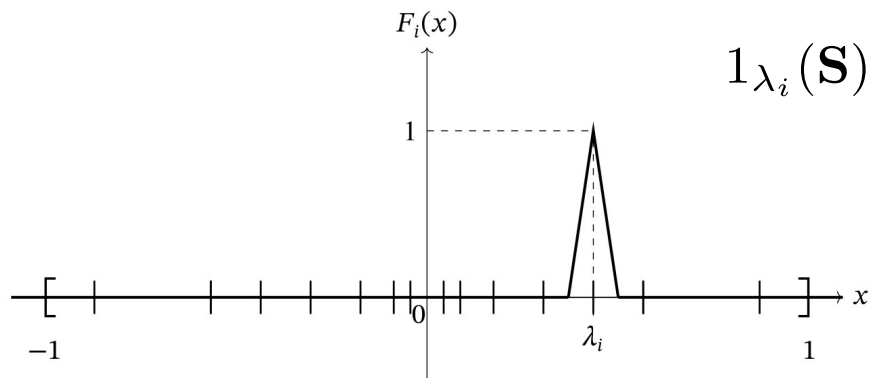
$$1_{\lambda_i}(\mathbf{S})f = \langle f, \phi_i \rangle \phi_i \quad \|1_{\lambda_i}(\mathbf{S})f\| = |\langle f, \phi_i \rangle| = \langle f, \phi_i \rangle$$

$$\frac{1_{\lambda_i}(\mathbf{S})f}{\|1_{\lambda_i}(\mathbf{S})f\|} = \phi_i$$

Actual GNNs?

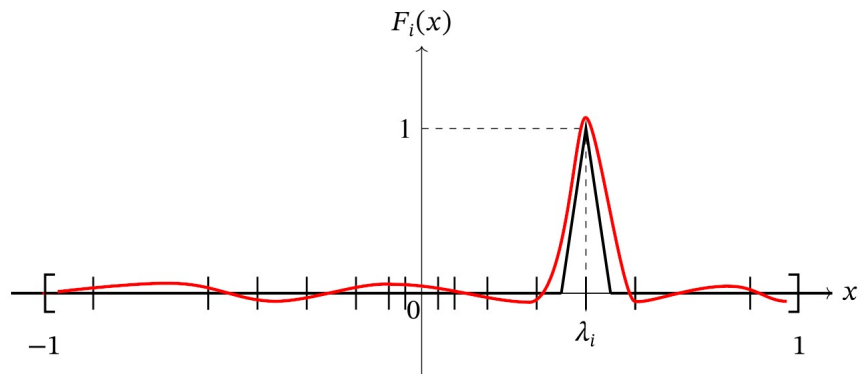
All this spectral stuff is a bit weird. Can we recover the eigenfunctions by actual GNNs?

Since eigenvalues are separated and $\mathcal{K} \subset \mathcal{D}^+$, ϕ_i can be recovered by filtering and normalization



$$1_{\lambda_i}(\mathbf{S})f = \langle f, \phi_i \rangle \phi_i \quad \|1_{\lambda_i}(\mathbf{S})f\| = |\langle f, \phi_i \rangle| = \langle f, \phi_i \rangle$$

$$\frac{1_{\lambda_i}(\mathbf{S})f}{\|1_{\lambda_i}(\mathbf{S})f\|} = \phi_i$$



Since universality is up to ϵ , they can even be replaced by polynomial filters!

$$\frac{Q_i(\mathbf{S})f}{\|Q_i(\mathbf{S})f\|} \approx \phi_i$$

Actual cGNNs

Theorem:

cGNNs are universal on domains $\mathcal{K} \subset \mathcal{D}^+$

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Proof:

$$\sum_{j=1}^m \text{MLP}_{\theta_j} \left(\left[\|Q_i(\mathbf{S})f\| \right]_{i=1}^m \right) \frac{Q_j(\mathbf{S})f}{\|Q_j(\mathbf{S})f\|} \quad \text{are universal}$$

Actual cGNNs

Theorem:

cGNNs are universal on domains $\mathcal{K} \subset \mathcal{D}^+$

Proof: $\sum_{j=1}^m \text{MLP}_{\theta_j} \left(\left[\left\| Q_i(\mathbf{S})f \right\| \right]_{i=1}^m \right) \frac{Q_j(\mathbf{S})f}{\left\| Q_j(\mathbf{S})f \right\|}$ are universal

↑
*Nothing more than **regular cGNNs!!** (with intermediate global poolings)*

- **Polynomial filtering**

- **Global pooling** to compute norm/inner products $\|f\|_{L^2}^2 \approx \frac{1}{n} \sum_i f(x_i)^2$

- All operations (multiplication, normalization, square root...) can be **approximated by MLPs**

Conclusion

- “From discrete to continuous” is a fruitful approach for GNNs
- Link with Neural Operators
- Still many things to explore/understand in the continuous world!

Outlooks

- Getting rid of the weird sign assumption?

→ **SignNet**-like architecture [*Lim et al. 2022*]:

$$\langle f, \phi_i \rangle \leftarrow \text{MLP}(\langle f, \phi_i \rangle) + \text{MLP}(-\langle f, \phi_i \rangle)$$

$$\phi_i \leftarrow \text{MLP} \circ \phi_i + \text{MLP} \circ (-\phi_i)$$

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- More general **Message-Passing** GNN? (GANs...)

→ **Convergence** is known

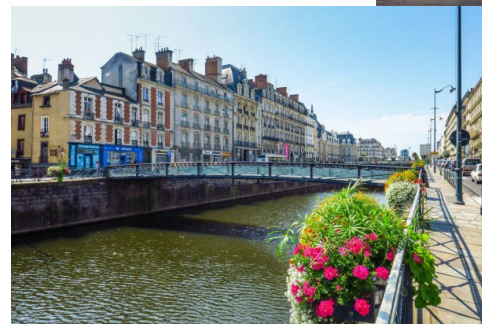
Non-linear operator filtering!

Cordonnier et al., *Convergence of Message Passing Graph Neural Networks with Generic Aggregation On Large Random Graphs*, 2023

Thank you!



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